



# basic education

Department:  
Basic Education  
**REPUBLIC OF SOUTH AFRICA**

**NATIONAL  
SENIOR CERTIFICATE  
NASIONALE  
SENIOR SERTIFIKAAT**

**GRADE/GRAAD 12**

**PHYSICAL SCIENCES: PHYSICS (P1)  
FISIESE WETENSKAPPE: FISIKA (V1)**

**NOVEMBER 2011**

**MEMORANDUM**

**MARKS/PUNTE: 150**

**This memorandum consists of 13 pages.  
*Hierdie memorandum bestaan uit 13 bladsye.***

## SECTION A

### QUESTION 1 / VRAAG 1

- 1.1 Power ✓  
*Drywing / Arbeidstempo* ✓ (1)
- 1.2 Coherent / *Koherent* ✓ (1)
- 1.3 Dielectric / *Diëlektrikum* ✓ (1)
- 1.4 Alternating (current) / AC / ac ✓  
*Wissel(stroom) / WS / ws* ✓ (1)
- 1.5  $N \cdot C^{-1} / V \cdot m^{-1}$  / newton per coulomb / volt per meter ✓ (1)
- [5]**

### QUESTION 2 / VRAAG 2

- 2.1 C ✓✓ (2)
- 2.2 D ✓✓ (2)
- 2.3 D ✓✓ (2)
- 2.4 C ✓✓ (2)
- 2.5 B ✓✓ (2)
- 2.6 A ✓✓ (2)
- 2.7 C ✓✓ (2)
- 2.8 C ✓✓ (2)
- 2.9 D ✓✓ (2)
- 2.10 B ✓✓ (2)
- [20]**

**TOTAL SECTION A / TOTAAL AFDELING A: 25**

**SECTION B / AFDELING B**

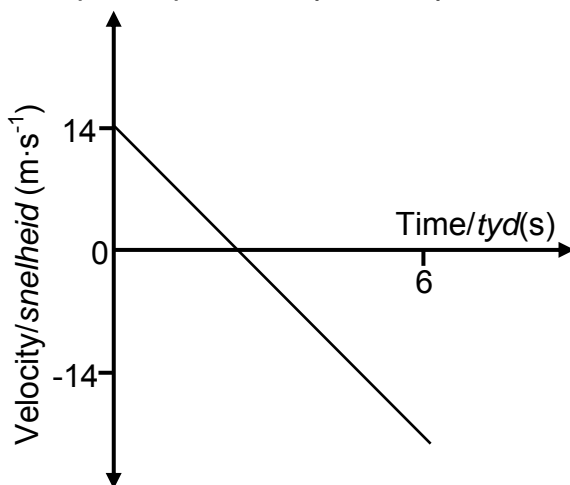
**QUESTION 3 / VRAAG 3**

3.1 The initial velocity / speed of the camera is the same ✓  
 (as that of the balloon).  
*Die beginsnelheid / spoed van die kamera is dieselfde* ✓ (as dié van die  
 ballon). (1)

3.2 **Downward positive:**  
**Afwaarts positief:**  
 $\Delta y = v_i \Delta t + \frac{1}{2} a \Delta t^2$  ✓  
 $\therefore 92,4 \checkmark = v_i(6) + \frac{1}{2}(9,8)(6)^2 \checkmark$   
 $\therefore v_i = -14 \text{ m}\cdot\text{s}^{-1}$   
 $\therefore v_i = 14 \text{ m}\cdot\text{s}^{-1} \checkmark$

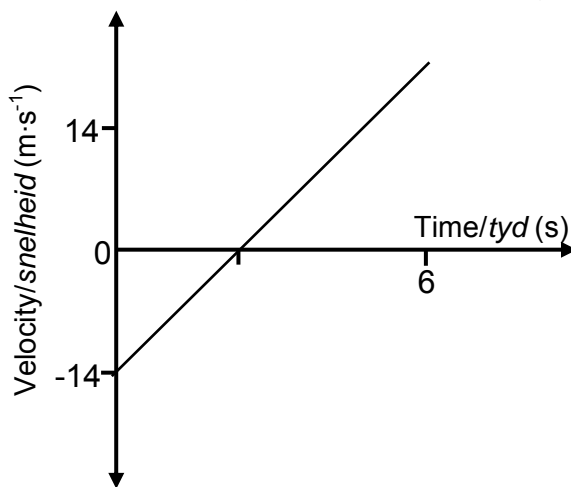
**Downward negative:**  
**Afwaarts negatief:**  
 $\Delta y = v_i \Delta t + \frac{1}{2} a \Delta t^2$  ✓  
 $\therefore -92,4 \checkmark = v_i(6) + \frac{1}{2}(-9,8)(6)^2 \checkmark$   
 $\therefore v_i = 14 \text{ m}\cdot\text{s}^{-1} \checkmark$  (4)

3.3 Upward positive/Opwaarts positief:



Criteria for graph/Kriteria vir grafiek:	Marks/Punte
Correct shape as shown.(straight line with gradient) Korrekte vorm soos getoon.(reguitlyn met gradient)	✓
Graph starts at $v = 14 \text{ m}\cdot\text{s}^{-1}$ / $v_i$ at $t = 0 \text{ s}$ . Grafiek begin by $v = 14 \text{ m}\cdot\text{s}^{-1}$ / $v_i$ by $t = 0 \text{ s}$ .	✓
Graph extends below t axis until $t = 6 \text{ s}$ . Grafiek verleng onder t-as tot $t = 6 \text{ s}$ .	✓
Section of graph below t axis longer than section above t axis. Gedeelte van grafiek onderkant t-as langer as gedeelte bokant t-as.	✓

Upward negative / Opwaarts negatief:



Criteria for graph/Kriteria vir grafiek:	Marks/Punte
Correct shape as shown. Korrekte vorm soos getoon.	✓
Graph starts at $v/v_i = -14 \text{ m}\cdot\text{s}^{-1}$ at $t = 0 \text{ s}$ . Grafiek begin by $v/v_i = -14 \text{ m}\cdot\text{s}^{-1}$ by $t = 0 \text{ s}$ .	✓
Graph extends above t axis until $t = 6 \text{ s}$ . Grafiek verleng bokant t-as tot $t = 6 \text{ s}$ .	✓
Section of graph above t axis longer than section below t axis. Gedeelte van grafiek bokant t-as langer as gedeelte onderkant t-as.	✓

(4)

3.4

<p><b>Option 1 / Opsie 1:</b>  <math>\Delta x = v\Delta t</math> ✓  <math>\therefore 10 \checkmark = (2)\Delta t \checkmark</math>  <math>\therefore \Delta t = 5 \text{ s} \checkmark</math>  <u>Yes/ Will catch the camera</u>, time is less than 6 s. ✓  <u>Ja / Sal die kamera vang</u>, tyd is kleiner as 6 s. ✓</p>
<p><b>Option 2/Opsie 2:</b>  <math>\Delta x = v\Delta t</math> ✓  <math>= (2)\checkmark(6) \checkmark</math>  <math>= 12 \text{ m} \checkmark</math>  <u>Yes / Will catch the camera</u>, distance covered is greater than 10 m. ✓  <u>Ja / Sal die kamera vang</u>, afstand afgelê is groter as 10 m. ✓</p>
<p><b>Option 3 / Opsie 3:</b>  <math>\Delta x = v_i\Delta t + \frac{1}{2}a\Delta t^2</math> ✓  <math>\therefore 10 \checkmark = (2)\Delta t \checkmark + \frac{1}{2}(0)\Delta t</math>  <math>\therefore \Delta t = 5 \text{ s} \checkmark</math>  <u>Yes/ will catch the camera</u>, time is less than 6 s ✓.  <u>Ja / Sal die kamera vang</u>, tyd is kleiner as 6 s. ✓</p>
<p><b>Option 4 / Opsie 4:</b>  <math>\Delta x = \left(\frac{v_i + v_f}{2}\right)\Delta t</math> ✓ <math>\therefore 10 \checkmark = \left(\frac{2+2}{2}\right)\Delta t \checkmark \therefore \Delta t = 5 \text{ s} \checkmark</math>  <u>Yes / Will catch the camera</u>, time is less than 6 s. ✓  <u>Ja / Sal die kamera vang</u>, tyd is kleiner as 6 s. ✓</p>
<p><b>Option 5 / Opsie 5:</b>  <math>\Delta x = \left(\frac{v_i + v_f}{2}\right)\Delta t</math> ✓ <math>= \left(\frac{2+2}{2}\right)\checkmark 6 \checkmark = 12 \text{ m}\cdot\checkmark</math>  <u>Yes / Will catch the camera</u>, distance covered is greater than 10 m. ✓  <u>Ja / Sal die kamera vang</u>, afstand afgelê is groter as 10 m. ✓</p>

(5)  
[14]

**QUESTION 4 / VRAAG 4**

4.1  $30 \text{ m}\cdot\text{s}^{-1}$  ✓ east / oos ✓

**Notes / Aantekeninge:**

$$v_{TP} = v_{TG} - v_{PG} = 40 - 10 = 30$$

$$\therefore v_{TP} = 30 \text{ m}\cdot\text{s}^{-1} \text{ east/oos}$$

**OR/OF**

$$v_{TP} = v_{TG} + v_{GP} = 40 + (-10) = 30$$

$$\therefore v_{TP} = 30 \text{ m}\cdot\text{s}^{-1} \text{ east/oos}$$

(2)

4.2  $70 \text{ m}\cdot\text{s}^{-1}$  ✓ east / oos ✓

**Notes / Aantekeninge:**

**Solution 1 / Oplossing 1:**

$$v_{BT} = v_{BP} - v_{TP}$$

$$= 100 - 30 = 70$$

$$\therefore v_{BT} = 70 \text{ m}\cdot\text{s}^{-1} \text{ east / oos}$$

**Solution 2 / Oplossing 2**

$$v_{BT} = v_{BP} + v_{PT}$$

$$= 100 + (-30) = 70$$

$$\therefore v_{BT} = 70 \text{ m}\cdot\text{s}^{-1} \text{ east/oos}$$

**OR / OF**

$$v_{BT} = v_{BP} + v_{PG} + v_{GT}$$

$$= 100 + 10 + (-40)$$

$$= 70$$

$$\therefore v_{BT} = 70 \text{ m}\cdot\text{s}^{-1} \text{ east / oos}$$

**Solution 3 / Oplossing 3**

$$v_{BT} = v_{BP} + v_{PG} + v_{GT}$$

$$= 100 + 10 + (-40)$$

$$= 70$$

$$\therefore v_{BT} = 70 \text{ m}\cdot\text{s}^{-1} \text{ east / oos}$$

**Solution 4 / Oplossing 4**

$$v_{BG} = v_{BP} + v_{PG}$$

$$= 100 + 10 = 110$$

$$\therefore v_{BG} = 110 \text{ m}\cdot\text{s}^{-1}$$

$$v_{BT} = v_{BG} + v_{GT}$$

$$= 110 + (-40) = 70$$

$$\therefore v_{BT} = 70 \text{ m}\cdot\text{s}^{-1} \text{ east / oos}$$

(2)

4.3 The total (linear) momentum remains constant/is conserved / does not change. ✓  
 in an isolated/a closed system/the absence of external forces. ✓

*Die totale (liniêre) momentum bly konstant / behoue / verander nie ✓  
 in 'n geïsoleerde sisteem / geslote sisteem / die afwesigheid van eksterne kragte. ✓*

(2)

4.4

<p><b>Option 1 / Opsie 1:</b> To the right as positive / Na regs as positief: <math>\Sigma p_{\text{before/ voor}} = \Sigma p_{\text{after/ na}} \checkmark</math> <math>(1\ 000)(40) \checkmark + (5\ 000)(-20) \checkmark = (1\ 000 + 5\ 000)v_f \checkmark</math> <math>\therefore v_f = -10\ \text{m}\cdot\text{s}^{-1} \checkmark</math> <math>\therefore v_f = 10\ \text{m}\cdot\text{s}^{-1}</math> <u>left / na links</u> <math>\checkmark</math> <b>OR / OF</b> west / wes</p>
<p><b>Option 2 / Opsie 2:</b> To the right as positive / Na regs as positief: <math>\Delta p_{\text{car}} = -\Delta p_{\text{truck}} \checkmark</math> <math>m(v_f - v_i) = -m(v_f - v_i)</math> <math>(1000)(v_f - (40)) \checkmark = -(5\ 000)(v_f \checkmark - (-20)) \checkmark</math> <math>6\ 000v_f = -60\ 000</math> <math>\therefore v_f = -10\ \text{m}\cdot\text{s}^{-1} \checkmark</math> <math>\therefore v_f = 10\ \text{m}\cdot\text{s}^{-1}</math> <u>left / na links</u> <math>\checkmark</math> <b>OR/OF</b> west / wes</p>

(6)

4.5

<p><b>Option 1 / Opsie 1:</b> Force on car / Krag op motor: To the right as positive / Na regs as positief: <math>F_{\text{net}}\Delta t = \Delta p \checkmark = mv_f - mv_i</math> <math>F_{\text{net}}(0,5) \checkmark = \frac{1\ 000(-10 - 40)}{1000} \checkmark</math> <math>\therefore F_{\text{net}} = -1 \times 10^5\ \text{N} \checkmark</math> <b>OR/OF</b> <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N}</math> (100 000 N)  <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal. / Ja botsing is fataal. <math>\checkmark</math></p>	<p>Force on car / Krag op motor: To the left as positive / Na links as positief: <math>F_{\text{net}}\Delta t = \Delta p \checkmark = mv_f - mv_i</math> <math>F_{\text{net}}(0,5) \checkmark = \frac{1\ 000(10 - (-40))}{1000} \checkmark</math> <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N} \checkmark</math> (100 000 N)  <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal. / Ja, botsing is fataal. <math>\checkmark</math></p>
<p><b>Option 2 / Opsie 2:</b> Force on truck / Krag op vragmotor: To the right as positive / Na regs as positief: <math>F_{\text{net}}\Delta t = \Delta p \checkmark = mv_f - mv_i</math> <math>F_{\text{net}}(0,5) \checkmark = \frac{5\ 000(-10 - (-20))}{1000} \checkmark</math> <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N} \checkmark</math> (100 000 N)  <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal. / Ja, botsing is fataal. <math>\checkmark</math></p>	<p>Force on truck / Krag op vragmotor: To the left as positive / Na links as positief: <math>F_{\text{net}}\Delta t = \Delta p \checkmark = mv_f - mv_i</math> <math>F_{\text{net}}(0,5) \checkmark = \frac{5\ 000(10 - 20)}{1000} \checkmark</math> <math>\therefore F_{\text{net}} = -1 \times 10^5\ \text{N} \checkmark</math> <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N}</math> (100 000 N) <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal / Ja, botsing is fataal. <math>\checkmark</math></p>
<p><b>Option 3 / Opsie 3:</b> Force on car / Krag op motor: To the right as positive / Na regs as positief: <math>v_f = v_i + a \Delta t</math> <math>\therefore -10 = 40 + a(0,5) \checkmark</math> <math>\therefore a = -100</math> <math>F_{\text{net}} = ma = (1\ 000)(-100) \checkmark</math> <math>\therefore F_{\text{net}} = -1 \times 10^5\ \text{N} \checkmark</math> (-100 000 N) <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N}</math> (100 000 N) <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal. / Ja, botsing is fataal. <math>\checkmark</math></p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin-left: auto; margin-right: auto;"> <p><math>\checkmark</math> Both formulae/ Beide formules</p> </div>	<p>Force on car / Krag op motor: To the left as positive / Na links as positief: <math>v_f = v_i + a \Delta t</math> <math>\therefore 10 = -40 + a(0,5) \checkmark</math> <math>\therefore a = 100</math> <math>F_{\text{net}} = ma = (1\ 000)(100) \checkmark</math> <math>\therefore F_{\text{net}} = 1 \times 10^5\ \text{N} \checkmark</math> (100 000 N)  <math>\therefore F_{\text{net}} &gt; 85\ 000\ \text{N}</math> Yes, collision is fatal. / Ja, botsing is fataal. <math>\checkmark</math></p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin-left: auto; margin-right: auto;"> <p><math>\checkmark</math> Both formulae/ Beide formules</p> </div>

<p><b>Option 4 / Opsie 4:</b> Force on truck / <i>Krag op vragsmotor:</i> To the right as positive / <i>Na regs as positief:</i></p> <p><math>v_f = v_i + a \Delta t</math> <math>\therefore -10 = -20 + a(0,5) \checkmark</math> <math>\therefore a = 20</math> <math>F_{net} = ma = (5\ 000)(20) \checkmark</math> <math>\therefore F_{net} = 1 \times 10^5 \text{ N} \checkmark (100\ 000 \text{ N})</math> <math>\therefore F_{net} &gt; 85\ 000 \text{ N}</math> Yes, collision is fatal. / <i>Ja, botsing is fataal.</i> <math>\checkmark</math></p>	<p>Force on truck / <i>Krag op vragsmotor:</i> To the left as positive / <i>Na links as positief:</i></p> <p><math>v_f = v_i + a \Delta t</math> <math>\therefore 10 = 20 + a(0,5) \checkmark</math> <math>\therefore a = -20</math> <math>F_{net} = ma = (5\ 000)(-20) \checkmark</math> <math>\therefore F_{net} = -1 \times 10^5 \text{ N} \checkmark (-100\ 000 \text{ N})</math> <math>\therefore F_{net} = 1 \times 10^5 \text{ N} (100\ 000 \text{ N})</math> <math>\therefore F_{net} &gt; 85\ 000 \text{ N}</math> Yes, collision is fatal. / <i>Ja, botsing is fataal.</i> <math>\checkmark</math></p>
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(5)  
[17]

**QUESTION 5 / VRAAG 5**

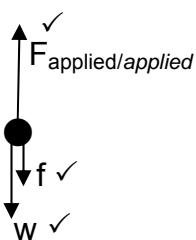
- 5.1 The net (total) work (done on an object)  $\checkmark$   
is equal to the change in kinetic energy (of the object.)  $\checkmark$   
*Die netto (totale) arbeid (verrig op 'n voorwerp)  $\checkmark$*   
*is gelyk aan die verandering in kinetiese energie (van die voorwerp)  $\checkmark$*

**OR / OF**

- The work done (on an object) by a net (resultant) force  $\checkmark$   
is equal to the change in (the object's) kinetic energy.  $\checkmark$   
*Die arbeid verrig (op 'n voorwerp) deur 'n netto (resulterende) krag  $\checkmark$*   
*is gelyk aan die verandering in kinetiese energie (van die voorwerp.)  $\checkmark$*

(2)

5.2



(3)

- 5.3 Gravitational force/weight (of soldier)  $\checkmark$   
*Gravitasiekrag/gewig (van soldaat)*

(1)

- 5.4  $W_{net} = \Delta K \checkmark$

$$F \Delta y \cos \theta + F_w \Delta y \cos \theta + W_f = \Delta K$$

$$(960)(20) \cos 0^\circ \checkmark + (80)(9,8)(20) \cos 180^\circ \checkmark + W_f = 0 \checkmark$$

$$19\ 200 - 15\ 680 + W_f = 0$$

$$W_f = -3\ 520 \text{ J} \checkmark$$

(5)  
[11]

**QUESTION 6 / VRAAG 6**

6.1 Doppler effect / Doppler-effek ✓ (1)

6.2  $f_L = \frac{v \pm v_L}{v \pm v_s} f_s$  ✓  
 $\therefore f_L = \frac{340 \pm 0}{340 - 20} \checkmark$  (458) ✓  
 $\therefore f_L = 486,63 \text{ Hz}$  ✓ (4)

6.3 Decreases/Verlaag ✓ (1)

6.4 Equal to/Gelyk aan ✓

Velocity of train driver relative to the whistle is zero. ✓  
*Snelheid van treindrywer relatief tot fluitjie is nul.*

**OR / OF**

Train driver has same velocity as whistle.  
*Treindrywer het dieselfde snelheid as die fluitjie.*

**OR / OF**

There is no relative motion between source and observer.  
*Daar is geen relatiewe beweging tussen bron en waarnemer.* (2)  
**[8]**

**QUESTION 7 / VRAAG 7**

7.1 Light of a single wavelength OR single frequency. ✓✓  
*Lig van 'n enkele golflengte* OF enkele frekwensie. ✓✓ (2)

7.2

Criteria for investigative question: <i>Kriteria vir ondersoekende vraag:</i>	Mark/ Punt
The <u>dependent</u> and <u>independent</u> variables are stated. <i>Die afhanklike en onafhanklike veranderlikes is genoem.</i>	✓
Asks a question about the relationship between <u>dependent</u> and <u>independent</u> variables. <i>Vra 'n vraag oor die verwantskap tussen die afhanklike en onafhanklike veranderlikes.</i>	✓

**Examples/Voorbeelde:**

- How will the broadness / width of the central band change / differ when slit width changes / is increased / is decreased?

*Hoe sal die breedte / wydte van die sentrale helderband verander / verskil wanneer die spleetwydte verander / toeneem / afneem?*

- What is the relationship between the broadness of the central bright band and slit width?

*Wat is die verwantskap tussen die breedte van die sentrale helderband en spleetwydte?* (2)



- 7.3 Wavelength (of light) / Frequency (of light) / Colour of light/ Light source ✓  
Distance between slit and screen. ✓

*Golflengte (van lig) / Frekwensie (van lig) / Kleur van lig / Ligbron ✓*  
*Afstand tussen spleet en skerm.* ✓

(2)

- 7.4 Increases / Vermeerder ✓  
Diffraction is inversely proportional to slit width. ✓  
*Diffraksie is omgekeerd eweredig aan spleetwydte.* ✓

**OR/OF**

Increases / Vermeerder ✓

Diffraction / *Diffraksie* OR/OF  $\sin \theta \propto \frac{1}{a}$  ✓

(2)

- 7.5 **Option 1 / Opsie 1:**

$$\sin \theta = \frac{m\lambda}{a} \checkmark$$

$$\sin \theta = \frac{(2)(4 \times 10^{-7})}{2,2 \times 10^{-6}} \checkmark$$

$$\therefore \theta = 21,32^\circ \checkmark$$

**Option 2 / Opsie 2:**

$$\sin \theta = \frac{m\lambda}{a} \checkmark$$

$$\sin \theta = \frac{(-2)(4 \times 10^{-7})}{2,2 \times 10^{-6}} \checkmark$$

$$\therefore \theta = -21,32^\circ \checkmark$$

(5)

[13]

**QUESTION 8 / VRAAG 8**

- 8.1 T to/na P ✓ (1)

8.2  $Q = \frac{3 \times 10^{-9} + (-6 \times 10^{-9})}{2} \checkmark = -1,5 \times 10^{-9} \text{ C}$

$$\begin{aligned} \Delta Q_P &= Q_P(\text{final}) - Q_P(\text{initial}) \\ &= -1,5 \times 10^{-9} - 3 \times 10^{-9} \checkmark \\ &= -4,5 \times 10^{-9} \text{ C} \checkmark \end{aligned}$$

**OR / OF**

$$\begin{aligned} \Delta Q_T &= Q_T(\text{final}) - Q_T(\text{initial}) \\ &= -1,5 \times 10^{-9} - (-6 \times 10^{-9}) \checkmark \\ &= 4,5 \times 10^{-9} \text{ C} \checkmark \end{aligned}$$

(3)

- 8.3 Number of electrons / *Getal elektrone* =  $\frac{-4,5 \times 10^{-9}}{-1,6 \times 10^{-19}} \checkmark$   
 $= 2,81 \times 10^{10} \checkmark$  (2)

8.4

<p><b>Option 1 / Opsie 1</b></p> $F_{TR} = \frac{kQ_1Q_2}{r^2} \checkmark$ $= \frac{(9 \times 10^9)(1,5 \times 10^{-9})(3 \times 10^{-9})}{1^2} \checkmark$ <p style="text-align: center;">= 4,05 x 10<sup>-8</sup> N to the left/towards P na links/na P toe</p>		<div style="border: 1px solid black; padding: 5px; width: fit-content; margin: auto;">                 ✓ Any one Enige een             </div>
$F_{PR} = \frac{kQ_1Q_2}{r^2}$ $= \frac{(9 \times 10^9)(1,5 \times 10^{-9})(3 \times 10^{-9})}{0,5^2} \checkmark$ <p style="text-align: center;">= 1,62 x 10<sup>-7</sup> N to the right/towards T na regs/na T toe</p>		
<p>To the right / towards T as positive: / Na regs / na T toe as positief</p> $F_{net} = 1,62 \times 10^{-7} - 4,05 \times 10^{-8}$ $= 1,22 \times 10^{-7} \text{ N } (1,215 \times 10^{-7} \text{ N})$ $= 1,22 \times 10^{-7} \text{ N } \checkmark \text{ to the right / towards T / na regs / na T toe } \checkmark$		

(6)  
[12]

**QUESTION 9 / VRAAG 9**

9.1 Current / I / stroom ✓ (1)

9.2  
9.2.1 (4,0 ✓ ; 0,64) ✓ (2)

9.2.2 Temperature was not kept constant. ✓✓  
Temperatuur is nie konstant gehou nie. ✓✓ (2)

9.3 Gradient/m =  $\frac{\Delta y}{\Delta x} = \frac{0,64 - 0}{4 - 0} \checkmark = 0,16$

$R = \frac{1}{0,16} = 6,25 \Omega \checkmark \checkmark$  (4)  
[9]

**QUESTION 10 / VRAAG 10**

10.1 12 V ✓ (1)

<p><b>Option 1 / Opsie 1:</b></p> $I = \frac{V}{R} \checkmark = \frac{9,6}{2,4} \checkmark = 4 \text{ A}$	<p><b>Option 2 / Opsie 2:</b></p> $\text{emf} = IR + Ir \checkmark$ $12 = I(2,4) + 2,4 \checkmark \therefore I = 4 \text{ A} \checkmark$
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(3)

10.2.2	<p><b>Option 1 / Opsie 1:</b>  <math>emf/emk = IR + Ir \checkmark</math>  <math>12 = 9,6 + 4r \checkmark</math>  <math>\therefore r = 0,6 \Omega \checkmark</math></p>	<p><b>Option 2 / Opsie 2:</b>  <math>V_{lost/verlore} = Ir \checkmark</math>  <math>2,4 = 4r \checkmark</math>  <math>\therefore r = 0,6 \Omega \checkmark</math></p>
	<p><b>Option 3 / Opsie 3:</b>  <math>emf/emk = I(R + r) \checkmark</math>  <math>12 = 4(2,4 + r) \checkmark \therefore r = 0,6 \Omega \checkmark</math></p>	

(3)

10.3

<p><b>Option 1 / Opsie 1:</b>  <math>emf/emk = I(R + r) \checkmark</math>  <math>12 = 6(R + 0,6) \checkmark</math>  <math>R_{ext/eks} = 1,4 \Omega</math>  <math>\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} \checkmark</math>  <math>\frac{1}{1,4} = \frac{1}{2,4} + \frac{1}{R} \checkmark</math>  <math>\therefore R = 3,36 \Omega</math>                  Each tail lamp/Elke agterlig:  <math>\therefore R = 1,68 \Omega \checkmark</math></p>	<p><b>Option 2 / Opsie 2:</b>  <math>Emf = V_{terminal} + Ir \checkmark</math>  <math>12 = V_{terminal} + 6(0,6) \checkmark</math>  <math>\therefore V_{terminal} = 8,4 V</math>  <math>I_{2,4 \Omega} = \frac{V}{R} = \frac{8,4}{2,4} = 3,5 A</math>  <math>I_{tail\ lamps/agterligte} = 6 - 3,5 = 2,5 A</math>  <math>R_{tail\ lamps/agterligte} = \frac{V}{I} \checkmark = \frac{8,4}{2,5} \checkmark = 3,36 \Omega</math>  <math>R_{tail\ lamp/agterlig} = 1,68 \Omega \checkmark</math></p>
<p><b>Option 3 / Opsie 3:</b>  <math>V = IR \checkmark</math>  <math>12 = (6)R \checkmark</math>  <math>R_{ext} = 2 \Omega</math>  <math>\therefore R_{parallel} = 2 - 0,6 = 1,4 \Omega</math>  <math>\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} \checkmark</math>  <math>\frac{1}{1,4} = \frac{1}{2,4} + \frac{1}{R} \checkmark</math>  <math>\therefore R = 3,36 \Omega</math>                  Each tail lamp/Elke agterlig: <math>R = 1,68 \Omega \checkmark</math></p>	<p><b>Option 4 / Opsie 4:</b>                  For parallel combination: <math>I_1 + I_2 = 6 A</math>                  Vir parallelle kombinasie: <math>I_1 + I_2 = 6 A</math>  <math>\therefore \frac{V}{2,4} + \frac{V}{R_{taillamps}} \checkmark = 6 \checkmark</math>  <math>8,4 \checkmark \left( \frac{1}{2,4} + \frac{1}{R_{taillamps}} \right) \checkmark = 6</math>  <math>\therefore R_{tail\ lamps/agterligte} = 3,36</math>  <math>R_{tail\ lamp/agterligte} = 1,68 \Omega \checkmark</math></p>

(5)

- 10.4 Increases / Vermeerder  $\checkmark$   
Resistance increases, current decreases  $\checkmark$   
Ir (lost volts) decreases  $\checkmark$   
 Vermeerder  $\checkmark$   
Weerstand verhoog, stroom verlaag  $\checkmark$   
Ir (verlore volts) verminder / neem af.  $\checkmark$

(3)  
[15]

**QUESTION 11 / VRAAG 11**

- 11.1.1 Electrical (energy) to mechanical / kinetic (energy) ✓  
*Elektriese (energie) na meganiese / kinetiese (energie) ✓* (1)
- 11.1.2 Mechanical / kinetic (energy) to electrical (energy) ✓  
*Meganiese / kinetiese (energie) na elektriese (energie) ✓* (1)
- 11.1.3 Motor effect / *Motor-effek* ✓ (1)
- 11.1.4 Electromagnetic induction ✓  
*Elektromagnetiese induksie ✓* (1)
- 11.2 BC / conductor is parallel ✓ to the magnetic field. ✓  
*BC / geleier is parallel ✓ aan die magneetveld. ✓*

**OR / OF**

- Open switch ✓, no current. ✓  
*Oop skakelaar ✓, geen stroom. ✓* (2)

11.3

<p><b>Option 1 / Opsie 1:</b></p> $P_{ave} = V_{rms} I_{rms} \checkmark$ $= \frac{V_{max}}{\sqrt{2}} \checkmark \cdot \frac{I_{max}}{\sqrt{2}} \checkmark$ $= \frac{(311)(21)}{2} \checkmark \checkmark$ $= 3\,265,5 \text{ W} \checkmark$ <p><b>OR / OF</b></p> $P_{max} = V_{max} I_{max} \checkmark$ $= (311) \checkmark (21) \checkmark$ $= 6531 \text{ W}$ $\therefore P_{ave} = \frac{P_{max}}{2} \checkmark \checkmark = \frac{6531}{2}$ $= 3\,265,5 \text{ W} \checkmark$	<p><b>Option 2 / Opsie 2:</b></p> $V_{rms} = \frac{V_{max}}{\sqrt{2}} \checkmark$ $= \frac{311}{\sqrt{2}} \checkmark$ $= 219,91 \text{ V}$ $I_{rms} = \frac{I_{max}}{\sqrt{2}} \checkmark$ $= \frac{21}{\sqrt{2}} \checkmark$ $= 14,85 \text{ A}$ $P_{ave} = V_{rms} I_{rms} \checkmark$ $= (219,91)(14,85)$ $= 3\,265,66 \text{ W} \checkmark$
<p><b>Option 3 / Opsie 3</b></p> $R = \frac{V}{I} \checkmark = \frac{311}{21} \checkmark = 14,81 \Omega$ $I_{rms} = \frac{I_{max}}{\sqrt{2}} \checkmark$ $= \frac{21}{\sqrt{2}} \checkmark$ $= 14,85 \text{ A}$ $P_{ave} = I_{rms}^2 R \checkmark$ $= (14,85)^2 (14,81)$ $= 3\,265,83 \text{ W} \checkmark$	<p><b>Option 4 / Opsie 4</b></p> $R = \frac{V}{I} \checkmark = \frac{311}{21} \checkmark = 14,81 \Omega$ $V_{rms} = \frac{V_{max}}{\sqrt{2}} \checkmark$ $= \frac{311}{\sqrt{2}} \checkmark$ $= 219,91 \text{ V}$ $P_{ave} = \frac{V_{rms}^2}{R} \checkmark$ $= \frac{219,41^2}{14,81}$ $= 3\,265,83 \text{ W} \checkmark$

(6)  
**[12]**

**QUESTION 12 / VRAAG 12**

12.1 Photo-electric effect / *Foto-elektriese effek* ✓ (1)

12.2 Work function / *Werkfunksie / Arbeidsfunksie* ✓ (1)

12.3  $c = f\lambda$  ✓  
 $3 \times 10^8$  ✓ =  $f(330 \times 10^{-9})$  ✓  
 $\therefore f = 9,09 \times 10^{14}$  Hz ✓

**OR/OF**

$$E = \frac{hc}{\lambda} = \frac{(6,63 \times 10^{-34})(3 \times 10^8)}{330 \times 10^{-9}} \checkmark = 6,03 \times 10^{-19} \text{ J}$$

$$E = hf$$

$$6,03 \times 10^{-19} = (6,63 \times 10^{-34})f \checkmark$$

$$\therefore f = 9,09 \times 10^{14} \text{ Hz} \checkmark$$

✓ for both equations  
*vir beide vergelykings*

(4)

12.4

**Option 1 / Opsie 1:**

$$\left. \begin{aligned} E &= W_o + K \\ \frac{hc}{\lambda} &= W_o + K \end{aligned} \right\} \checkmark \text{ Any one / Enige een}$$

$$\therefore \frac{(6,63 \times 10^{-34})(3 \times 10^8)}{330 \times 10^{-9}} \checkmark = 3,5 \times 10^{-19} + K \checkmark$$

$$\therefore K = 2,53 \times 10^{-19} \text{ J} \checkmark$$

**Option 2 / Opsie 2:**

$$\left. \begin{aligned} E &= W_o + K \\ hf &= W_o + K \end{aligned} \right\} \checkmark \text{ Any one / Enige een}$$

$$\therefore (6,63 \times 10^{-34})(9,09 \times 10^{14}) \checkmark = 3,5 \times 10^{-19} + K \checkmark$$

$$\therefore K = 2,53 \times 10^{-19} \text{ J} \checkmark$$

(4)

12.5

12.5.1 Remains the same / *Bly dieselfde* ✓ (1)

12.5.2 Increases / *Vermeerder* ✓ (1)

12.6

12.6.1 Ultraviolet radiation / *Ultraviolet-straling* ✓ (1)

12.6.2 High energy / high frequency ✓  
Hoë energie / hoë frekwensie (1)

[14]

**TOTAL SECTION B/TOTAAL AFDELING B: 125**  
**GRAND TOTAL/GROOTTOTAAL: 150**